

MOTORS

Brakes & Clutches

Combinorm - Power On

The Combinorm are electro-magnetically actuated, single face, clutches and brakes for dry operation.

On the brake, the current is applied and the force due to the magnetic field is used to produce the brake torque. The armature is pulled axially against the brake magnet resulting in a friction locked connection without backlash. When the current is switched off the armature is separated from the brake magnet by a riveted steel spring. This separation ensures that no residual torque occurs regardless of the installation position, so that even at high idling speeds no friction losses occur.

With the clutches, the current is applied and the force due to the magnetic field is used to transmit torque. The armature is pulled axially against the rotor resulting in a friction locked connection without backlash. When the current is switched off the armature is separated from the rotor by a riveted steel spring. This separation ensures that no residual torque occurs regardless of the installation position, so that even at high idling speeds no friction losses occur.

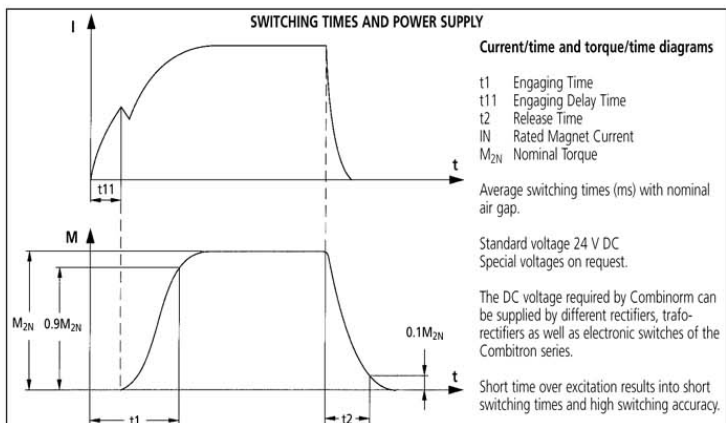
Hub supplied with a pilot bore.

Combinorm Electro-magnetic Brakes and Clutches

- Asbestos free wear resistant and temperature stable Friction Linings
- 100% duty, unlimited 'on' period.
- Short switching times with low operating noise
- Backlash free
- No residual torque
- Maintenance Free
- High stable torque capacity
- CSA, VDE & TUV certification, LV CE, Insulation class B
- Excellent repeatability, long life and ease of installation
- Operates at 24V DC

Applications

- Stairlifts
- Wheelchairs
- Start/Stop applications
- Automation Systems
- Indexing Machines
- Rotary Tables
- Machine Tools
- Pick and Place



| Size | | 01 | 02 | 03 | 05 | 06 | 07 | 08 | 09 | 10 | 11 | 12 |
|----------|-------------------------|----|----|----|----|----|----|-----|-----|-----|-----|-----|
| CLUTCHES | t11 nominal voltage | 4 | 5 | 7 | 10 | 14 | 18 | 23 | 25 | 29 | 37 | 55 |
| | t1 | 10 | 14 | 17 | 32 | 48 | 74 | 81 | 90 | 161 | 201 | 295 |
| | t11 3 x nominal voltage | 2 | 2 | 3 | 5 | 6 | 8 | 10 | 12 | 14 | 16 | 25 |
| | t1 | 5 | 6 | 7 | 16 | 22 | 33 | 37 | 42 | 69 | 91 | 125 |
| | t2 DC | 5 | 6 | 7 | 10 | 14 | 19 | 40 | 68 | 100 | 130 | 200 |
| | t2 AC | 17 | 19 | 22 | 30 | 39 | 61 | 115 | 220 | 400 | 650 | 900 |
| BRAKES | t11 nominal voltage | 2 | 3 | 3 | 5 | 6 | 8 | 10 | 13 | 15 | 23 | 35 |
| | t1 | 5 | 8 | 8 | 17 | 24 | 38 | 42 | 48 | 85 | 118 | 155 |
| | t11 3 x nominal voltage | 1 | 2 | 2 | 3 | 3 | 4 | 5 | 6 | 8 | 10 | 16 |
| | t1 | 3 | 4 | 4 | 8 | 11 | 17 | 20 | 22 | 38 | 50 | 76 |
| | t2 DC | 3 | 4 | 5 | 8 | 10 | 15 | 50 | 85 | 100 | 140 | 200 |
| | t2 AC | 17 | 20 | 25 | 40 | 70 | 95 | 240 | 300 | 400 | 600 | 800 |

MOTORS

Brakes & Clutches

Combinorm - Power On

TECHNICAL DATA

| Size | | 01 | 02 | 03 | 05 | 06 | 07 | 08 | 09 | 10 | 11 | 12 | |
|----------------------|--------------------|---------------------------------|-------|-------|-------|-------|-------|------|------|------|------|------|------|
| Moments of Inertia J | ROTORS | | | | | | | | | | | | |
| | Picture | B4, B5, B7, B10 | 0.025 | 0.035 | 0.15 | 0.375 | 0.825 | 2.38 | 7.25 | 21.9 | 67.4 | 200 | 450 |
| | | B7, B11 | 0.027 | 0.038 | 0.17 | 0.40 | 0.9 | 2.6 | 8.0 | 24.0 | 73.0 | 220 | 500 |
| | | B8 B10 | | | | | 1.02 | 30.5 | 8.76 | 26.0 | 82.5 | 230 | 520 |
| | ARMATURES | | | | | | | | | | | | |
| | Picture | B2, B5, B6, B7, B8, B10, B11 a) | 0.010 | 0.045 | 0.045 | 0.122 | 0.366 | 1.07 | 3.72 | 10.6 | 40.0 | 115 | 311 |
| | | B2, B5, B6, B7, B10, B11 b) | 0.013 | 0.068 | 0.068 | 0.18 | 0.53 | 1.57 | 5.29 | 15.1 | 50.1 | 159 | 437 |
| | | B3 b) | | | | | 0.82 | 2.6 | 10.3 | 27.0 | 101 | | |
| | | B4 b) | | | | | 0.99 | 2.7 | 9.12 | 25.4 | 88.9 | 272 | 814 |
| | | HUB | | | | | 0.16 | 0.49 | 0.89 | 3.77 | 19.9 | 41.2 | 118 |
| INTERMEDIATE RING | | | | | B9 | | | | | | | | |
| | | | | | | 1.5 | 5.0 | 11.0 | 30.0 | 112 | 253 | 814 | |
| RUBBER ELEMENT | Picture | | | | | 0.35 | 1.25 | 3.3 | 7.0 | 50.2 | 102 | 450 | |
| Switching work, wear | W _{R max} | | 0.04 | 0.05 | 0.08 | 0.12 | 0.19 | 0.31 | 0.48 | 0.75 | 1.25 | 2.0 | 2.9 |
| | W _{RO.1} | | 0.23 | 0.30 | 0.43 | 0.63 | 0.95 | 1.63 | 2.53 | 4.09 | 6.66 | 10.4 | 16.3 |
| | P _{R max} | clutch | 20.3 | 28.6 | 40.6 | 58.3 | 80.6 | 114 | 161 | 228 | 322 | 458 | 647 |
| | P _{R max} | brake | 12.8 | 18.6 | 26.9 | 38.9 | 58.3 | 79.2 | 114 | 164 | 236 | 339 | 489 |
| | X _n | | 0.3 | 0.45 | 0.45 | 0.6 | 0.7 | 0.7 | 0.7 | 0.9 | 1.0 | 1.2 | 1.2 |
| | X | | 0.1 | 0.15 | 0.15 | 0.2 | 0.2 | 0.2 | 0.2 | 0.3 | 0.3 | 0.4 | 0.4 |
| | n max | | 10000 | 10000 | 10000 | 10000 | 8000 | 6000 | 5000 | 4000 | 3000 | 3000 | 2000 |

Legend

| | |
|--------------------|--|
| W _{R max} | permissible friction per switching operation 10 ⁴ J |
| W _{RO.1} | friction work up to 0.1mm wear 10 ⁷ J |
| P _{R max} | permissible friction work per second |
| X _m | clearance at which an adjustment is recommended mm |
| X | rated air gap mm |
| n | speed |

Single-face clutches and brakes obtain the torques listed in the table without difficulty after a run-in phase of 100 min-1. In the new state or in case of substantially higher speed the torque may under certain circumstances be smaller.

Dimensioning

Decisive for the dimensioning of the Combinorm are the required torque, thermal load, braking time and service life.

Rated Torque M_{2N}

To ensure that Combinorm safely works even under extreme conditions, the required torque must be multiplied by a safety factor. The selection of the safety factor depends essentially on the application.

$$M_{2N} = M_{\text{erf}} \cdot K \quad K \geq 2 \quad M_{\text{erf}} = \text{required torque (Nm)}$$

Required Torque M_{erf}

The required torque very often is a mixture of dynamic and static load. Observe sign!

$$M_{\text{erf}} = M_A \pm M_L \\ M_A = J \cdot \alpha$$

Rough Definition of the required Torque

If the mass moment of inertia is unknown and the driving power is fixed then the required torque is calculated as follows:

$$M_{\text{erf}} = 9550 \cdot \frac{P}{n}$$

Thermal Load

The dimensioning solely on the basis of the required torque is permissible only in very few cases. When decelerating or accelerating the load and the mass moment of inertia reduced to the shaft, the kinetic energy is converted into heat (friction work). The permissible friction work may not be exceeded.

$$W_R = \frac{J \cdot n^2}{182.5} \cdot \frac{M_{2N}}{M_{2N} \pm M_L} \quad W_R \leq W_{R\text{max}}$$

Slip time t₃ (ms)

$$t_3 = 104.6 \cdot \frac{J \cdot \Delta n}{M_{2N} \pm M_L} + t_{11}$$

Service Life in Switching Operations until Readjustment

With the variable Xn the service life can be calculated until the readjustment.

The variable Xn is a recommended value. According to the application it must be checked when the readjustment has to be made.

$$L_n = \frac{(X_n - X) \cdot W_{RO.1}}{0.1 \cdot W_R}$$